

Communicative rotary actuator for rotary valves and butterfly valves

- Torque motor 40 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative, hybrid
- Communication via BACnet MS/TP, Modbus RTU, Belimo-MP-Bus or conventional control
- Conversion of sensor signals





echnical data		
Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V
	Power consumption in operation	4 W
	Power consumption in rest position	1.5 W
	Power consumption for wire sizing	7 VA
	Connection supply / control	Cable 1 m, 6 x 0.75 mm ²
Data bus communication	Communicative control	BACnet MS/TP Modbus RTU (default setting) MP-Bus
	Number of nodes	BACnet / Modbus see interface description MP-Bus max. 8
Functional data	Torque motor	40 Nm
	Operating range Y	210 V
	Operating range Y variable	0.510 V
	Position feedback U	210 V
	Position feedback U note	Max. 1 mA
	Position feedback U variable	Start point 0.58 V End point 210 V
	Position accuracy	±5%
	Manual override	with push-button, can be locked
	Running time motor	90 s / 90°
	Running time motor variable	75270 s
	Adaptation setting range	manual (automatic on first power-up)
	Override control, controllable via bus communication	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position) = 50%
	Override control variable	MAX = (MIN + 33%)100% MIN = 0%(MAX – 33%) ZS = MINMAX
	Sound power level, motor	45 dB(A)
	Position indication	Mechanical, pluggable
Safety data	Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)
	Power source UL	Class 2 Supply
	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 2
	Enclosure	UL Enclosure Type 2
	EMC	CE according to 2014/30/EU

Certification IEC/EN

IEC/EN 60730-1 and IEC/EN 60730-2-14

GR24A-MOD-7

MP/2/BUS°



reclifical data sheet	GRZ4A-MOD-7
UL Approval	cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1 The UL marking on the actuator depends on the production site, the device is UL-compliant in any case
Type of action	Type 1
Rated impulse voltage supply / control	0.8 kV
Pollution degree	3
Ambient humidity	Max. 95% RH, non-condensing
Ambient temperature	-3050°C [-22122°F]
Storage temperature	-4080°C [-40176°F]
Servicing	maintenance-free
Connection flange	F07

Safety notes



Weight

Weight

Mechanical data

Safety data

 This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.

2.3 kg

- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The switch for changing the direction of rotation may only be operated by authorised specialists. The direction of rotation must not in particular be reversed in a frost protection circuit.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.

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• The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

Mode of operation

The actuator is fitted with an integrated interface for BACnet MS/TP, Modbus RTU and MP-Bus. It receives the digital control signal from the control system and returns the current status.

Converter for sensors

Connection option for a sensor (passive, active or with switching contact). In this way, the analogue sensor signal can be easily digitised and transferred to the bus systems: BACnet, Modbus or MP-Bus.

Parametrisable actuators

The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.

The communication parameters of the bus systems (address, baud rate etc.) are set with the ZTH EU. Pressing the "Address" button on the actuator while connecting the supply voltage, resets the communication parameters to the factory setting.

Quick addressing: The BACnet and Modbus address can alternatively be set using the buttons on the actuator and selecting 1...16. The value selected is added to the «Basic address» parameter and results in the effective BACnet and Modbus address.

Combination analogue - communicative

(hybrid mode)

With conventional control by means of an analogue control signal, BACnet or Modbus can be used for the communicative position feedback

Simple direct mounting

Simple direct mounting on the rotary valve or butterfly valve with mounting flange. The mounting orientation in relation to the fitting can be selected in 90° steps.



Technical data sheet

GR24A-MOD-7

Manual override

Manual override with push-button possible (the gear train is disengaged for as long as the

button is pressed or remains locked).

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.

High functional reliability

The actuator is overload protected, requires no limit switches and automatically stops when the

end stop is reached.

Home position

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator ${\bf r}$

carries out an adaptation, which is when the operating range and position feedback adjust

themselves to the mechanical setting range.

The actuator then moves into the position defined by the control signal.

Factory setting: Y2 (counter-clockwise rotation).

Adaptation and synchronisation

An adaptation can be triggered manually by pressing the "Adaptation" button or with the PC-

Tool. Both mechanical end stops are detected during the adaptation (entire setting range).

 $\label{thm:configured} \textbf{Automatic synchronisation after pressing the manual override button is configured. The}$

synchronisation is in the home position (0%).

The actuator then moves into the position defined by the control signal.

A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

Accessories

Tools	Description	Type
	Service Tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH EU
	Belimo PC-Tool, Software for adjustments and diagnostics Adapter for Service-Tool ZTH Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to	MFT-P MFT-C ZK1-GEN
	service socket Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN

Electrical installation



Supply from isolating transformer.

The wiring of the line for BACnet MS/TP / Modbus RTU is to be carried out in accordance with applicable RS-485 regulations.

Modbus / BACnet: Supply and communication are not galvanically isolated. Connect earth signal of the devices with one another.

Wire colours:

1 = black

2 = red

3 = white 5 = orange

6 = pink

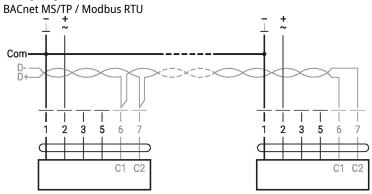
7 = grey

Functions:

C1 = D - = AC2 = D + = B



Wiring diagrams

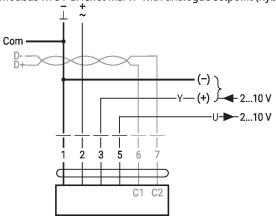


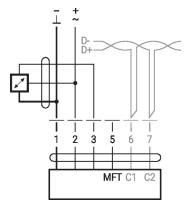
Functions

Functions with specific parameters (Parametrisation necessary)

Modbus RTU / BACnet MS/TP with analogue setpoint (hybrid mode)

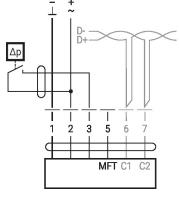
Connection with active sensor, e.g. 0...10 V @ 0...50°C





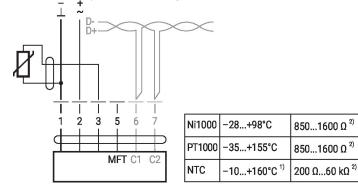
Possible input voltage range: 0...10 V Resolution 30 mV

Connection with switching contact, e.g. Δp monitor



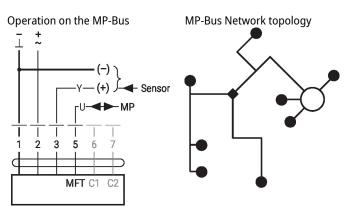
Switching contact requirements: The switching contact must be able to switch a current of 16 mA at 24 V accurately. Start point of the operating range must be parametrised on the MOD actuator as $\geq 0.5 \text{ V}$.

Connection with passive sensor, e.g. Pt1000, Ni1000, NTC



1) depending on type
2) Resolution 1 Ohm
Compensation of the measured value is recommended





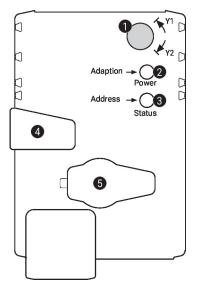
There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted).

Supply and communication in one and the same 3-wire cable

- no shielding or twisting necessary
- no terminating resistors

required

Operating controls and indicators



Direction of rotation switch

Switch over: Direction of rotation changes

2 Push-button and LED display green

Off: No power supply or malfunction

On: In operation

Flashing: In address mode: Pulses according to set address (1...16)

When starting: Reset to factory setting (Communication)

Press In standard mode: Triggers angle of rotation adaptation button: In address mode: Confirmation of set address (1...16)

Push-button and LED display yellow

Off: Standard mode

On: Adaptation or synchronisation process active

or actuator in address mode (LED display green flashing)

Flickering: BACnet / Modbus communication active

Press In operation (>3 s): Switch address mode on and off button: In address mode: Address setting by pressing several times

When starting (>5 s): Reset to factory setting (Communication)

4 Manual override button

Press button: Gear train disengages, motor stops, manual override possible

Release button: Gear train engages, standard mode

5 Service plug

For connecting parametrisation and service tools

Check power supply connection

2 Off and 3 On Possible wiring error in power supply



Service

Quick addressing

- 1. Press the "Address" button until the green "Power" LED is no longer illuminated. LED flashes in accordance with the previously set address.
- 2. Set the address by pressing the "Address" button the corresponding number of times (1...16).
- 3. The green LED flashes in accordance with the address that has been entered (...16). If the address is not correct, then this can be reset in accordance with Step 2.
- 4. Confirm the address setting by pressing the green "Adaptation" button.

If no confirmation occurs for 60 seconds, then the address procedure is ended. Any address change that has already been started will be discarded.

The resulting BACnet MS/TP and Modbus RTU address is made up of the set basic address plus the short address (e.g. 100+7=107).

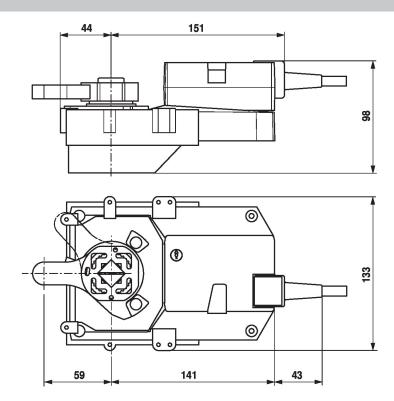
Tools connection

The actuator can be parametrised by ZTH EU via the service socket.

For an extended parametrisation the PC tool can be connected.



Dimensions





Further documentation

- Tool connections
- BACnet Interface description
- Modbus Interface description
- Overview MP Cooperation Partners
- MP Glossary
- The complete product range for water applications
- Data sheets for ball valves
- Installation instructions for actuators and/or ball valves
- General notes for project planning