

Technical data sheet

Rotary actuator fail-safe for rotary valves and butterfly valves

- Torque motor 40 Nm
- Nominal voltage AC/DC 24 V
- Control Open/close



Technical data

| Electrical data | Nominal voltage | AC/DC 24 V |
|-----------------|--|---|
| | Nominal voltage frequency | 50/60 Hz |
| | Nominal voltage range | AC 19.228.8 V / DC 21.628.8 V |
| | Power consumption in operation | 11 W |
| | Power consumption in rest position | 3 W |
| | Power consumption for wire sizing | 21 VA |
| | Power consumption for wire sizing note | Imax 20 A @ 5 ms |
| | Connection supply / control | Cable 1 m, 2 x 0.75 mm ² |
| | Parallel operation | Yes (note the performance data) |
| Functional data | Torque motor | 40 Nm |
| | Setting fail-safe position | NC/NO, adjustable (POP rotary knob) |
| | Bridging time (PF) | 2 s |
| | Manual override | with push-button |
| | Running time motor | 150 s / 90° |
| | Running time fail-safe | 35 s / 90° |
| | Sound power level, motor | 52 dB(A) |
| | Sound power level, fail-safe | 61 dB(A) |
| | Position indication | Mechanical |
| Safety data | Protection class IEC/EN | III, Safety Extra-Low Voltage (SELV) |
| | Power source UL | Class 2 Supply |
| | Degree of protection IEC/EN | IP54 |
| | Degree of protection NEMA/UL | NEMA 2 |
| | Enclosure | UL Enclosure Type 2 |
| | EMC | CE according to 2014/30/EU |
| | Certification IEC/EN | IEC/EN 60730-1 and IEC/EN 60730-2-14 |
| | UL Approval | cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1 |
| | | The UL marking on the actuator depends on |
| | | the production site, the device is UL-compliant |
| | | in any case |
| | Type of action | Туре 1.АА |
| | Rated impulse voltage supply / control | 0.8 kV |
| | Pollution degree | 3 |
| | Ambient humidity | Max. 95% RH, non-condensing |
| | Ambient temperature | -3050°C [-22122°F] |
| | Storage temperature | -4080°C [-40176°F] |
| | Servicing | maintenance-free |
| Mechanical data | Connection flange | F05 |
| Weight | Weight | 2.8 kg |
| | | |



Terms Abbreviations

POP = Power off position / fail-safe position CPO = Controlled power off / controlled failsafe

PF = Power fail delay time / bridging time

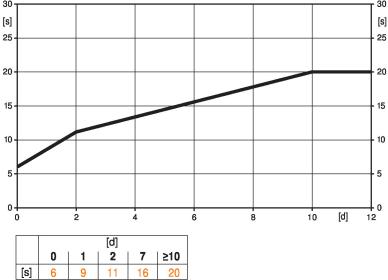
Safety notes



- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

| Mode of operation | The actuator moves the valve to the desired operating position at the same time as the integrated capacitors are loaded. Interrupting the supply voltage causes the valve to be moved to the selected fail-safe position by means of stored electrical energy. | |
|------------------------------|--|--|
| Pre-charging time (start up) | IP) The capacitor actuators require a pre-charging time. This time is used for charging the capacitors up to a usable voltage level. This ensures that, in the event of a power failure, the actuator can move at any time from its current position into the preset fail-safe position. The duration of the pre-charging time depends mainly on how long the power was interrupted. | |
| | Typical pre-charging time | |
| | 30 30 | |



[d] = Electricity interruption in days [s] = Pre-charging time in seconds

Delivery condition (capacitors)

Setting fail-safe position (POP)

The actuator is completely discharged after delivery from the factory, which is why the actuator requires approximately 20 s pre-charging time before initial commissioning in order to bring the capacitors up to the required voltage level.

The rotary knob fail-safe position can be used to adjust the desired fail-safe position. In the event of a power failure, the actuator drives to the selected fail-safe position, taking into account the bridging time (PF) of 2 s set at the factory.



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| Simple direct mounting | Simple direct mounting on the rotary valve or butterfly valve with mounting flange. The mounting orientation in relation to the fitting can be selected in 90° steps. | |
|------------------------------|---|--|
| Manual override | Manual control with push-button possible - temporary. The gear train is disengaged and the actuator decoupled for as long as the button is pressed. | |
| Adjustable angle of rotation | Adjustable angle of rotation with mechanical end stops. | |
| High functional reliability | The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached. | |

Accessories

| Electrical accessories | Description | Туре |
|------------------------|--|---------|
| | Auxiliary switch 1 x SPDT add-on | S1A |
| | Auxiliary switch 2 x SPDT add-on | S2A |
| | Feedback potentiometer 140 Ω add-on | P140A |
| | Feedback potentiometer 200 Ω add-on | P200A |
| | Feedback potentiometer 500 Ω add-on | P500A |
| | Feedback potentiometer 1 k Ω add-on | P1000A |
| | Feedback potentiometer 2.8 kΩ add-on | P2800A |
| | Feedback potentiometer 5 k Ω add-on | P5000A |
| | Feedback potentiometer 10 kΩ add-on | P10000A |

Electrical installation



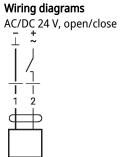
Supply from isolating transformer.

Parallel connection of other actuators possible. Observe the performance data. Direction of rotation switch is covered. Factory setting: Direction of rotation Y2.

Wire colours:

1 = black 2 = red

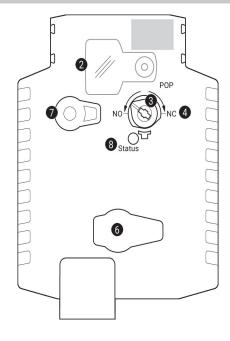
Wiring diagrams



| 1 | 2 | 國 |
|---|-----|---------------|
| 7 | _/L | A - AB = 0% |
| ł | ζ | A - AB = 100% |



Operating controls and indicators



2 Cover, POP button

3 POP button

4 Scale for manual adjustment

6 (no function)

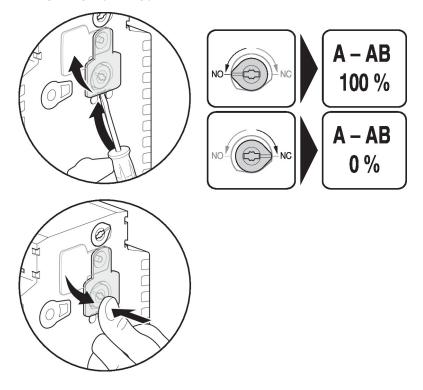
Manual override button

Press button:Gear train disengages, motor stops, manual override possibleRelease button:Gear train engages, standard mode

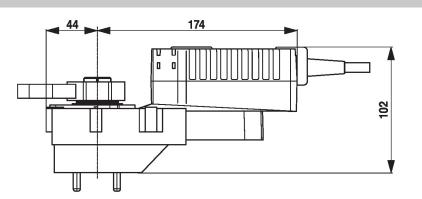
LED displays

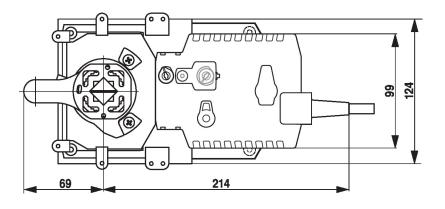
| green 8 | Meaning / function | |
|----------|------------------------------|--|
| On | Operation OK | |
| Flashing | POP function active | |
| Off | - Not in operation | |
| | - Pre-charging time SuperCap | |
| | - Fault SuperCap | |

Setting emergency setting position (POP)









Further documentation

- The complete product range for water applications
- Data sheets for rotary valves and butterfly valves
- Installation instructions for actuators and/or rotary valves and butterfly valves
- General notes for project planning